



HOME OF SENSOR TECHNOLOGY

Description of
RS485 MODBUS interface

WRF06 AQ Modbus
FTW06 Modbus
WRF06 Temp Modbus

Revision

Revision	Date	Description	Editor
A	18.06.2018	First issue	DF
B	06.07.2018	FTW06 / cross table products added	DF
C	06.01.2020	Type WRF06 Temp added	DF

Table of Contents

1	General	3
1.1	Hardware Installation.....	4
1.2	RS485 Transceiver	4
1.3	Protocol.....	4
1.4	Configuration Options.....	4
2	Modbus Register Description	5
2.1	Sensor Value.....	5
2.2	Offset-/Correction Values	6
2.3	Measuring Values Upper-/Lower Limits	7
2.4	Sensor Configuration.....	8
2.5	General Registers	9
2.6	Display Configuration.....	10
3	Modbus Protocol.....	11
3.1	Supported Control Commands	11
3.2	Data Transmission.....	11
3.2.1	Master/Slave Protocol	11
3.2.2	Data Frame	11
3.2.3	Transmission Mode RTU	12

1 General

This document describes the RS485 Modbus interface for the following devices:

- WRF06 AQ RS485 Modbus
- FTW06 RS485 Modbus
- WRF06 Temp RS485 Modbus

Depending on the device type and configuration level not all measuring values and configuration parameters shown in this document are available. The corresponding values are defined in the overview below.

	Temperature	relative humidity	absolute humidity	Enthalpy	Dew point	CO2	VOC	CO2 VOC Mix
WRF06 CO2						•		
WRF06 CO2 Temp	•					•		
WRF06 CO2 Temp_rH	•	•	•	•	•	•		
WRF06 CO2+VOC						•	•	•
WRF06 VOC Temp	•						•	
WRF06 CO2+VOC Temp_rH	•	•	•	•	•	•	•	•
FTW06	•	•	•	•	•			
WRF06 Temp	•							

1.1 Hardware Installation

The device can be connected by means of a twisted-pair cable (line resistance 120 Ohm).

Detailed information on the installation and mounting can be found in the product data sheet of the corresponding device and the data sheet wiring_rs485_network.pdf.

1.2 RS485 Transceiver

The maximal number of bus participants without the use of a repeater is default by the RS485 transceiver.

The transceiver used in the device enables 32 devices per bus segment.

1.3 Protocol

The device is a slave bus participant which is only allowed to send to the bus on request of a master. The protocol is in accordance with the defaults of:

- [MODBUS Application Protocol Specification V1.1](#) (Link)
- [MODBUS over Serial Line Specification & Implementation guide V1.0](#) (Link)

1.4 Configuration Options

The device can be adapted to the corresponding bus topology by means of a dip switch.

- Bus address of device (1 - 63)
- Baud rate 9600, 19200, 38400 or 57600
- Even parity (even), uneven (odd) or none (none)
- The number of stop bits is determined automatically by the device depending on the parity
 - 1 Stop bit with parity „even“ or „odd“
 - 1 or 2 stop bits with parity „none“, configurable via dip switch

2 Modbus Register Description

All following registers listed are holding registers which are addressable via the Modbus function codes 3, 6 and 16 (0x03, 0x06 und 0x10).

In the column "Address" the data address of the respective register is listed. The "Access" column indicates whether the respective register is only readable (R - read only) or readable and writable (RW - read write). In addition, the data type of the respective register is specified in the "Access" column (u16 - unsigned 16 bit, s16 - signed 16 bit).

2.1 Sensor Value

Via the registers 0...7 different measuring values can be read out. Which measuring values are available in the respective devices can be inquired via the register 501 (sensor identification).

Address	Access	Description	default	Remarks
400	RW / u16	Selection of unit systems	1	1: SI 2: Imperial

Address	Access	Description	Resolution /Unit	
1	R / u16	Relative humidity	0.1	%rF
5	R / u16	CO2	1.0	ppm
6	R / u16	VOC	0.1	%
7	R / u16	CO2 VOC Mix	0.1	

Register 400 = 1 (unit SI)

Address	Access	Description	Resolution /Unit		
0	R / s16	Temperature	SI	0.1	°C
2	R / u16	Absolute humidity	SI	0.01	g/m ³
3	R / u16	Enthalpy	SI	0.1	kJ/kg
4	R / s16	Dew Point	SI	0.1	°C

Register 400 = 2 (unit Imperial)

Address	Access	Description	Resolution /Unit		
0	R / s16	Temperature	Imperial	0.1	°F
2	R / u16	Absolute humidity	Imperial	0.01	gr/ft ³
3	R / u16	Enthalpy	Imperial	0.1	BTU/lb
4	R / s16	Dew Point	Imperial	0.1	°F

2.2 Offset-/Correction Values

Via the registers 100...103 the offset/correction values for the single measuring values can be default.

Example: Offset Temperature (Register 100):

Offset +1 °C (+1 °F) = 10_{10} (0000'0000'0000'1010₂) = 00 0a₁₆

Offset -1 °C (-1 °F) = -10_{10} (1111'1111'1111'0110₂) = ff f6₁₆

Address	Access	Description	default	Resolution /Unit	
101	RW / s16	Offset relative humidity	0	1.0	%rF
102	RW / s16	Offset CO2	0	1.0	ppm
103	RW / s16	Offset VOC	0	1.0	%

Register 400 = 1 (unit SI)

Address	Access	Description	Unit	default	Resolution /Unit	
100	RW / s16	Offset Temperature	SI	0	0.1	°C

Register 400 = 2 (unit Imperial)

Address	Access	Description	Unit	default	Resolution /Unit	
100	RW / s16	Offset Temperature	Imperial	0	0.1	°F

2.3 Measuring Values Upper-/Lower Limits

Via the measuring values upper-/lower limits values in a special range can be localized. The scale concerns the values in the registers 0..7.

Address	Access	Description	default	Resolution /Unit	
202	RW / u16	Relative humidity lower limit	0	1.0	%rH
203	RW / u16	Relative humidity upper limit	100	1.0	%rH
210	RW / u16	CO2 lower limit	0	1.0	ppm
211	RW / u16	CO2 upper limit	5000	1.0	
212	RW / u16	VOC lower limit	0	1.0	%
213	RW / u16	VOC upper limit	100	1.0	
214	RW / u16	CO2 VOC Mix lower limit	0	1.0	%
215	RW / u16	CO2 VOC Mix upper limit	100	1.0	

Register 400 = 1 (unit SI)

Address	Access	Description	Unit	default	Resolution /Unit	
200	RW / s16	Temperature lower limit	SI	0	1.0	°C
201	RW / s16	Temperature upper limit	SI	50	1.0	°C
204	RW / u16	Absolute humidity lower limit	SI	0	1.0	g/m ³
205	RW / u16	Absolute humidity upper limit	SI	83	1.0	g/m ³
206	RW / u16	Enthalpy lower limit	SI	0	1.0	kJ/kg
207	RW / u16	Enthalpy upper limit	SI	274	1.0	kJ/kg
208	RW / s16	Dew point lower limit	SI	-110	1.0	°C
209	RW / s16	Dew point upper limit	SI	50	1.0	°C

Register 400 = 2 (unit Imperial)

Address	Access	Description	Unit	default	Resolution /Unit	
200	RW / s16	Temperature lower limit	Imperial	32	1.0	°F
201	RW / s16	Temperature upper limit	Imperial	122	1.0	°F
204	RW / u16	Absolute humidity lower limit	Imperial	0	1.0	gr/ft ³
205	RW / u16	Absolute humidity upper limit	Imperial	36	1.0	gr/ft ³
206	RW / u16	Enthalpy lower limit	Imperial	0	1.0	BTU/lb
207	RW / u16	Enthalpy upper limit	Imperial	637	1.0	BTU/lb
208	RW / s16	Dew point lower limit	Imperial	-166	1.0	°F
209	RW / s16	Dew point upper limit	Imperial	122	1.0	°F

2.4 Sensor Configuration

Via the register 400 the requested unit system can be selected

Address	Access	Description	default	Resolution /Unit
400	RW / u16	Selection of unit system	1	1: SI 2: Imperial

2.5 General Registers

Via the registers 501...503 general device information can be read out and written.

Address	Access	Description	Remarks
501	R / u16	Sensor identification	1=sensor value available 0= sensor value not available
			Bit 0: Temperature Bit 1: Relative humidity Bit 2: Absolute humidity Bit 3: Enthalpy Bit 4: Dew point Bit 5: CO2 Bit 6: VOC Bit 7: CO2 VOC Mix
502	R / u16	Hardware version main board	Example.: V 1.1 = 0x0101
503	R / u16	Firmware version main board	Readability in hexadecimal

2.6 Display Configuration

Via the registers 615 and 616 TLF parameters can be adapted

Address	Access	Description	default	Remarks
615	RW / u16	Traffic-light threshold - TLF Range 1→2 (green/yellow)	750 ppm	
616	RW / u16	Traffic-light threshold - TLF Range 2→3 (yellow/red)	1250 ppm	

3 Modbus Protocol

<http://www.modbus.org/>

3.1 Supported Control Commands

The following MODBUS control commands are supported by the device:

Description	Function Code	
Read Holding Register	03 (hex)	3 (dec)
Write Single Register	06 (hex)	6 (dec)
Write Multiple Register	10 (hex)	16 (dec)

3.2 Data Transmission

3.2.1 Master/Slave Protocol

One Master and one or several Slaves are connected to the serial bus. The communication between Master and Slave is solely controlled by the Master. Slaves are only allowed to send if they were called by the Master before. Slaves are only sending to a Master, never to another Slave.

3.2.2 Data Frame

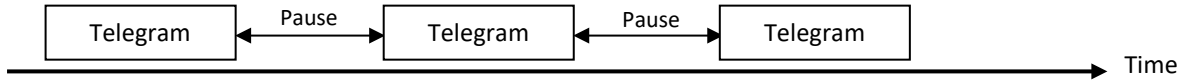
Data are sent to the bus in accordance with strictly defined defaults:

Address	Control Command	Data	Checksum
---------	-----------------	------	----------

In general a MODBUS telegram starts with the address of a slave, followed by a control command (e.g. read out of register) and the data. By means of the checksum at the end of the telegram the bus participants can recognize transmission errors.

3.2.3 Transmission Mode RTU

In the transmission mode RTU telegrams are separated by transmission pauses.



The period of the transmission pauses for separation of telegrams is depending on the set baud rate and amounts to $3,5 \cdot \text{Word-Transmission Time (11 Bit)}$. With 9600 Baud at least 4 ms and with 19200 at least 2ms must pass by between two telegrams.

3.2.3.1 Telegram Structure

Address 1 Byte	Control Command 1 Byte	Data 0 - 100 Byte	Checksum	
			Low	High

3.2.3.2 Calculation of CRC-Checksum

The CRC checksum (Cyclic Redundancy Check) is calculated by the sender by means of all bytes transmitted and is attached to the message. Then, the receiver calculates the CRC checksum again and compares the same with checksum received. If the values are not matching, a transmission error must be assumed and the data received are rejected. The low-order byte of the 16 bit checksum is sent in the telegram next to the last position and the high-order byte at the last position.

Calculation of Checksum (programming example in C):

```

crc = 0xFFFF; // CRC-Check, Init
for(i = 0; i < telegram_length-2; i++)
    crc = crc_calc(crc, telegram_data[i]);

crc_low = crc & 0x00FF; // Low-Byte
crc_high = (crc & 0xFF00) >> 8; // High-Byte

// Calculate CRC
unsigned int crc_calc(unsigned int crc_temp, unsigned int data)
{
    unsigned int Index_CC=0;
    unsigned int LSB=0;
    crc_temp = ( ( crc_temp ^ data ) | 0xFF00 ) & ( crc_temp | 0x00FF );
    for(Index_CC = 0; Index_CC<8; Index_CC++)
    {
        LSB = (crc_temp & 0x0001);
        crc_temp >>= 1;
        if(LSB)
            crc_temp = crc_temp ^ 0xA001; // calculation polynomial for CRC16
    }
    return(crc_temp);
}

```